Estimation of Surface Breakdown Voltage of Solid/Gas Composite Insulation with Embedded Electrode

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ABSTRACT

Solid insulated switchgear (SIS) has been developed as a substitution for medium voltage SF₆ gas insulated switchgear. Its main circuits including a vacuum interrupter are coated with epoxy resin, therefore, a solid/gas insulation system is formed. For further miniaturization and higher stress design of SIS, the authors investigated on the surface insulation of the solid/gas insulation system containing an embedded electrode. In the present study, the surface breakdown voltage was estimated based on the surface discharge propagation characteristics. From the measurement of the surface flashover voltage on a dielectric against the surface distance, the relation between the surface flashover voltage and the surface distance was found to be expressed with an equation derived from the empirical equation presented by Toepler. Then, the surface breakdown voltage was estimated based on the obtained equation. The estimated values were compared with the experimental data obtained varying a parameter of the radius of the embedded electrode, thickness of the epoxy resin plate or the radius of the plate. As a result, a good correlation was obtained. Therefore, the estimation method of the surface breakdown voltage on the solid/gas insulation with embedded electrode was established.

Index Terms - Composite insulation, electric breakdown, estimation, surface discharge, switchgear.

1 INTRODUCTION

IN an electric power system, switchgear is used for changing circuit connections. It also takes the role of isolating a fault when a problem occurs in the system. In that case, switchgear operates so that it isolates the fault within a minimum area and prevents a spread of the problem towards important equipment. Therefore, high reliability in operation is required for the switchgear.

Recently, most of the medium voltage switchgear is cubicle-type low pressure SF_6 gas insulated switchgear. However, SF_6 gas was designated as one of the targets of emission control in the global warming prevention conference held in 1997. Then, research and development of SF_6 gas free systems were actively advanced [1, 2].

Regarding the situation mentioned above, a solid insulated switchgear (SIS) has been developed [2]. The main circuits of

SIS including a vacuum interrupter are coated with epoxy resin. However, improvement of the surface insulation performance of the solid/gas composite insulation system is necessary for the development of higher stress and compact design.

Therefore, the authors investigated on the surface insulation of the solid/gas composite insulation system. In the previous study [3], metal electrode was embedded into the insulation material of epoxy resin and its effect on the insulation performance was investigated. In the present study, the surface discharge propagation characteristics were measured and the characteristics were found to be expressed with an equation derived from the empirical equation presented by Toepler. Then, the surface breakdown voltage was estimated based on the obtained equation. The estimated values were compared with the experimental data obtained by varying a parameter of the radius of the embedded electrode, thickness of the epoxy resin plate or the radius of the plate. As a result, a good

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correlation was obtained. Therefore, the estimation method of the surface breakdown voltage on the solid/gas insulation system with embedded electrode was established.

2 SURFACE BREAKDOWN MODEL

Figure 1 shows the cross section of a test sample of the solid/gas composite insulation system. This test sample was the model of insulation system of SIS and was composed of a disc-shaped epoxy resin plate with a back-side electrode and a disc-shaped embedded electrode. The back-side electrode was formed by painting a conductive layer on the underside of the insulation plate. The embedded electrode was made of copper with a thickness of 2 mm. It was rounded at the edge with a radius of curvature of 1 mm. The separation between the bottom of the embedded electrode was connected to the center rod electrode which was made of copper with a radius of 5 mm.



Figure 1. A model of composite insulation system with embedded electrode. r_p is the radius of the disc-type epoxy resin plate, r_e is the radius of the embedded electrode and t is the thickness of the epoxy resin plate [3].

In the previous study [3], the authors investigated on the surface breakdown voltage (BDV) and the partial discharge inception voltage (PDIV) by varying the radius of the embedded electrode (r_{e}) , thickness of the disc-type epoxy resin plate (t) or the radius of the epoxy resin plate $(r_{\rm p})$ under ac or impulse voltage application. As a result, it was found that the surface discharge initiated at the point of the maximum electric field strength along the surface and it propagated in both directions towards the center rod electrode and towards the ground electrode. The surface breakdown is supposed to be caused when both of the surface discharges reach the opposite electrodes. However, it is slightly complicated. The polarity of the surface discharge propagates on each surface is different. The electrostatic property of each surface is also different. Moreover, the applied voltage is divided into both surfaces.

In order to simplify the discussion, the authors introduce an imaginary electrode at the point of the maximum field strength. As shown in Figure 2, the surface can be separated into two parts according to the direction of the surface discharge propagation. If the polarity of the applied voltage is positive, a positive surface discharge propagates from the point of maximum field strength towards the ground and a negative one propagates from the point towards the center rod electrode. The electrostatic property of each surface is different, because the thickness of the epoxy resin is not the same.

Now, the authors introduce a hypothesis for the model of the surface breakdown process as follows.

- (a) If one of the surface discharges reaches the opposite electrode as shown in Figure 2b or 2c, the surface flashes over and all of the voltage is applied to the other surface.
- (b) Following (a), surface breakdown is accomplished if the applied voltage is high enough to flash over the other surface.



Figure 2. A separated surface model of composite insulation system with embedded electrode.

3 BDV ESTIMATION PROCEDURE

From the previous section, BDV of the test sample can be estimated based on the flashover characteristics of each surface in Figure 2. As already known widely, the surface flashover characteristics depend on the applied voltage and the distributed electrostatic capacity per unit area of a dielectric [4, 5]. However, the characteristics are slightly different among the researchers. In the present study, the characteristics were measured using disc-type epoxy resin plates experimentally. For BDV estimation the potential at the point of the maximum field strength is necessary. The potential was calculated using Ansoft Maxwell (Ansoft Japan Co., Ltd.) based on finite element method.

3.1 SURFACE FLASHOVER CHARACTERISTICS ON DIELECTRIC

The arrangement of electrodes and a dielectric for the measurement of the surface flashover characteristics is shown in Figure 3. Surface flashover characteristics were measured with disc-type epoxy resin plates without embedded electrode.

The specifications of the disc-type epoxy resin plates are shown in Table 1. The surface flashover characteristics were measured under impulse voltage application.

There are several equations which expressed the surface discharge propagation characteristics on a dielectric. Equation



Figure 3. Electrode arrangement for the measurement of the surface flashover characteristics.

Table 1. Specifications of test samples used for the examination of the surface discharge propagation characteristics.

Radius of the plate (mm)	Thickness of the plate (mm)	Distributed electrostatic capacity per unit area (F/m ²)
50	11	2.737 ×10 ⁻⁹
100	9	3.345 ×10 ⁻⁹
100	11	2.737 ×10 ⁻⁹
100	15	2.007 ×10 ⁻⁹
100	21	1.434 ×10 ⁻⁹
250	11	2.737 ×10 ⁻⁹

(1) is one of the equations which is an empirical equation presented by Toepler [4].

1

$$f_g = K_a V_g^4 C_a^{\frac{3}{2}}$$
(1)

where l_g (cm) is the surface discharge length, V_g (kV) is the applied voltage in peak value, C_a (pF/cm²) is the distributed electrostatic capacity per unit area and K_a is a constant. Toepler gave $K_a = 3.4 \times 10^{-5}$ for positive polarity.

From equation (1), the surface flashover voltage can be derived if we assume that the surface flashover takes place when the surface discharge reaches the opposite electrode. Then, the surface flashover voltage V (V) in peak value can be expressed as equation (2)

$$V = K_{\rm b} l^{\frac{1}{4}} C_{\rm b}^{-\frac{3}{8}}$$
(2)

where l (m) is the surface length, $C_{\rm b}$ (F/m²) is the distributed electrostatic capacity per unit area and K_b is a constant which is derived from K_a and is 73.6 for positive polarity.

Equation (2) can be used for both ac and impulse surface flashovers. However, ac surface flashover voltage is known to be affected by the conditions such as the surface resistance. Furthermore, the equations expressed the surface flashover characteristics are different among the researchers. Therefore, the relation between surface distance and surface flashover voltage was measured under impulse voltage in the present study.

The surface flashover voltage was measured with $1.2/50 \ \mu s$ impulse voltage and voltage elevation method. Voltage elevation was started from around 80 % of the estimated flashover voltage and the step was about 1 kV. Measurement was done more than 20 times for each condition of samples listed in Table 1 and the minimum value was employed as the measured flashover voltage. In the case of the measurement under impulse voltage application, the residual charge of

former discharge may influence on the surface flashover voltage. Consequently, the residual charge was removed before each voltage application. The influence was also examined without charge removal. The influence was revealed to vary with the kind of the applied voltage and the polarity in the case of impulse.

Figure 4 shows the relation between the surface flashover voltage and the surface distance. Figure 5 shows the relation between the surface flashover voltage and the thickness of the insulation plate. According to the variation of the thickness of the plate, the distributed electrostatic capacity per unit area varies as shown in Table 1. From these figures, the measured surface flashover voltages were found to be lower than the calculated values using equation (2). However, the variation of the flashover voltage was similar to the calculated values using equation (2).



Figure 4. Relation between surface flashover voltage and the surface distance (thickness of the plate was 11 mm).



Figure 5. Relation between surface flashover voltage and the thickness of the dielectric (radius of the plate was 100 mm).

Then, the authors assumed that the surface flashover voltage V is proportional to $l^{\frac{1}{4}}C_{\rm b}^{-\frac{3}{8}}$ as in equation (2), and the authors determined the values of K_b from the measured data with least squares method. It was 57.56 for positive and 67.25 for negative, respectively. Therefore, equation (2) was expressed in the following equations (3) and (4) which were used for the estimation of surface BDV. These equations are shown in Figures 4 and 5.

$$V_{\rm pos.} = 57.56 \, l^{\frac{1}{4}} C_{\rm b}^{-\frac{3}{8}} \tag{3}$$

$$V_{\rm neg.} = 67.25 \ l_{\rm 4}^{\frac{1}{4}} C_{\rm b}^{\frac{-8}{8}} \tag{4}$$

3.2 BDV ESTIMATION PROCEDURE

Firstly, we have to take the voltages across both surfaces, inner and outer into consideration. The divided voltages of inner and outer surfaces are expressed as follows

$$V_{\text{out.}} = DV_a \tag{5}$$
$$V_{\text{in}} = (1 - D)V_a \tag{6}$$

where $V_{\text{in.}}$ and $V_{\text{out.}}$ are the voltages applied inner and outer surfaces when the applied voltage is V_a . D ($0 \le D \le 1$) is the divided voltage ratio and DV_a also means the potential of the point of the maximum field strength to the ground. The potential was calculated using Ansoft Maxwell (Ansoft Japan Co., Ltd.). The obtained values of D will be shown in Table 2 (Section 4).

Secondly, we have to think about which surface flashes over first. The applied voltage when either surface flashes over is necessary. Substituting the surface flashover voltage for $V_{\rm in.}$ or $V_{\rm out.}$, the applied voltage when either surface flashes over can be obtained. However, the polarity of the applied voltage and the polarity of the surface discharge should be taken into consideration. There are three cases which are characterized according to the kind of the voltage applied to the center rod electrode and the polarity of the applied voltage.

Note that the thickness of inner and outer surfaces are different and the distributed electrostatic capacity per unit area is also different because C_b varies with the thickness of the dielectric. In the following equations, $C_b = C'_b$ means that the thickness is different from the thickness of the plate. $l_{in.}$ and $l_{out.}$ mean the lengths of the inner and outer surfaces, respectively.

(a) Positive impulse voltage application

 $V_{\text{pos.}}$ and $V_{\text{neg.}}$ should be substituted for $V_{\text{out.}}$ and $V_{\text{in.}}$, respectively.

$$V_{\rm F_{in.}} = \left(\frac{1}{1-D}\right) V_{\rm neg.} \quad (C_{\rm b} = C'_{\rm b}, \ l = l_{\rm in.}) \quad (7)$$
$$V_{\rm F_{out.}} = \frac{1}{D} V_{\rm pos.} \quad (l = l_{\rm out.}) \quad (8)$$

where $V_{\text{F}_{\text{in.}}}$ and $V_{\text{F}_{\text{out.}}}$ are the peak values of the applied voltage when inner and outer surfaces flash over, respectively.

(b) Negative impulse voltage application

 $V_{\text{neg.}}$ and $V_{\text{pos.}}$ should be substituted for $V_{\text{out.}}$ and $V_{\text{in.}}$, respectively.

$$V_{\rm F_{in.}} = \left(\frac{1}{1-D}\right) V_{\rm pos.} \quad (C_{\rm b} = C_{\rm b}', \ l = l_{\rm in.}) \ (9)$$
$$V_{\rm F_{out.}} = \frac{1}{D} V_{\rm neg.} \quad (l = l_{\rm out.}) \tag{10}$$

(c) Ac voltage application

The polarity of the surface discharge changes alternatively and the flashover voltage of positive polarity is lower than that of negative. Therefore, $V_{\text{pos.}}$ should be substituted for $V_{\text{in.}}$ and $V_{\text{out.}}$. Note that all of the voltages are expressed in peak values.

$$V_{\text{F}_{\text{in.}}} = \left(\frac{1}{1-D}\right) V_{\text{pos.}} \quad (C_{\text{b}} = C'_{\text{b}}, \ l = l_{\text{in.}}) \ (11)$$
$$V_{\text{F}_{\text{out.}}} = \frac{1}{D} V_{\text{pos.}} \quad (l = l_{\text{out.}}) \tag{12}$$

From the comparison between $V_{F_{in.}}$ and $V_{F_{out.}}$, which surface flashes over first can be revealed.

Finally, we have to compare the applied voltage when either surface flashes over first with the flashover voltage of un-shortened surface. As all of the applied voltage is assumed to be applied to the un-shortened surface, the surface breakdown takes place when the applied voltage is higher than the flashover voltage of un-shortened surface. On the other hand, if the applied voltage is lower than the flashover voltage of un-shortened surface, the flashover voltage of un-shortened surface becomes the surface breakdown voltage.

As it is slightly complicated, an example is introduced. Figure 6 shows an example of the calculated results in the case t = 11 (mm), $r_p = 100 \text{ (mm)}$, r_e is varied and negative impulse voltage is applied to the center rod electrode.

In the case where r_e is 5 mm, surface breakdown voltage, BDV is determined from the negative surface flashover voltage of the epoxy resin plate with the surface distance of 95 mm and the thickness of 11 mm

$$C_{\rm b} = \frac{\varepsilon_{\rm F} \times 8.854 \times 10^{-12}}{d} \tag{13}$$

where ε_r is the relative permittivity of 3.4, and *d* is the thickness of dielectric and is the same as the thickness of the plate of 11×10^{-3} m, under the present condition. Then, C_b becomes 2.737×10^{-9} F/m². BDV is determined as follows.

BDV =
$$V_{\text{Fout.}} = \frac{1}{D} V_{\text{neg.}}$$
 (14)
($C_{\text{b}} = 2.737 \times 10^{-9}, l = 95 \times 10^{-3}, D = 1$)

When r_e is larger than 5 mm, the thickness *d* of inner side becomes 5×10^{-3} m, because the thickness of the epoxy resin plate is 11 mm, the thickness of the embedded electrode is 2 mm and the distance between the embedded plate and the back-side electrode is 4 mm. Then, C_b becomes 6.021×10^{-9} F/m². However, $V_{F_{in.}}$ and $V_{F_{out.}}$ was calculated except for the small r_e region. In the case where $5 \le r_e \le 10$ (mm), the point of the maximum field strength appears at the surface of the center rod electrode. Then, BDV cannot be estimated according to the procedure mentioned above. The authors suppose that BDV in this region is almost the same as the case where $r_e = 5$ (mm). The particularity in this region will be explained again in DISCUSSION.



Figure 6. An example of surface flashover characteristics under negative impulse application. t = 11 (mm) and $r_p = 100$ (mm).

When $r_{\rm e}$ is 15 mm, $V_{\rm F_{in.}}$ is lower than $V_{\rm F_{out.}}$ that means the inner surface flashes over first. Then, BDV is obtained from the comparison between $V_{\rm F_{in.}}$ and the surface flashover voltage of the outer surface ($V_{\rm neg.}$). $V_{\rm F_{in.}}$ is higher than $V_{\rm neg.}$, then $V_{\rm F_{in.}}$ becomes BDV.

BDV =
$$V_{\text{Fin.}} = \left(\frac{1}{1-D}\right) V_{\text{pos.}}$$
 (15)
($C_{\text{b}} = C'_{\text{b}} = 6.021 \times 10^{-9}, l = 15 \times 10^{-3}$)

On the other hand, when r_e is larger than 25 mm ($r_e = 50$ (mm) for example), $V_{F_{out.}}$ is lower than $V_{F_{in.}}$ that means the outer surface flashes over first. Then, BDV is obtained from the comparison between $V_{F_{out.}}$ and the surface flashover voltage of the inner surface ($V_{pos.}$ where C_b is 6.021 x10⁻⁹ F/m²). $V_{F_{out.}}$ is higher than $V_{pos.}$, then $V_{F_{out.}}$ becomes BDV.

BDV =
$$V_{\text{F}_{\text{out.}}} = \frac{1}{D} V_{\text{neg.}}$$
 (16)
($C_{\text{b}} = 2.737 \times 10^{-9}, l = (100 - r_{\text{e}}) \times 10^{-3}$)

4 ESTIMATED BDV AND COMPARISON WITH EXPERIMENTS

According to the BDV estimation procedure, the surface breakdown voltage was calculated and was compared with the measured values.

4.1 SPECIFICATIONS OF SAMPLES

Table 2 shows the specifications of the test samples used in the measurement of the surface breakdown voltage.

The test samples were classified into three groups due to the variable which was one of three parameters of the test sample, $r_{\rm e}$, t or $r_{\rm p}$.

4.2 AC BDV

Figure 7 shows the relation between ac breakdown voltage (BDV) and the radius of the embedded electrode, r_e . Surface breakdown voltage was measured in the previous study [3] with voltage elevation method. Voltage elevation rate was about 3 kV/s. Measurement was done more than three times for each condition of samples listed in Table 2 and the minimum value was employed as BDV. Although the measured BDV is smaller than the estimated value when r_e is smaller than 25 mm, the measured BDV is almost the same as the estimated value when r_e is larger than 25 mm. The difference in the small r_e region will be explained in DISCUSSION.

Table 2. Specifications of test samples.

Radius of	Thickness of	Radius of the	Divided
the plate	the plate	embedded	voltage
(mm)	(mm)	Electrode (mm)	ratio, D
100	11	5	1.00
100	11	15	0.66
100	11	25	0.69
100	11	50	0.69
100	11	70	0.69
100	9	50	0.73
100	15	50	0.65
100	21	50	0.61
50	11	25	0.69
250	11	25	0.68



Figure 7. Relation between ac breakdown voltage and the radius of the embedded electrode. t = 11 (mm) and $r_p = 100 \text{ (mm)}$.



Figure 8. Relation between ac breakdown voltage and the thickness of the plate. $r_e = 50 \text{ (mm)}$ and $r_p = 100 \text{ (mm)}$.



Figure 9. Relation between ac breakdown voltage and the radius of the plate. $r_{\rm e} = 25$ (mm) and t = 11 (mm).

Figure 8 shows the relation between ac BDV and the thickness of the plate, t. There is a good correlation between the measured value and the estimated value. According to the increase of t, the distributed electrostatic capacity per unit area decreases and the surface flashover voltage increases. Therefore, the surface breakdown voltage increases with t.

Figure 9 shows the relation between ac BDV and the radius of the plate, r_p . The estimated value is higher than the measured value. The difference will be explained in DISCUSSION.

4.3 IMPULSE BDV

Figure 10 shows the relation between impulse breakdown voltage (BDV) and the radius of the embedded electrode, r_e . Surface breakdown voltage was measured in the previous study [3] with 1.2/50 µs impulse voltage and voltage elevation

method. Voltage elevation was started from around 80 % of the estimated breakdown voltage and the step was about 1 kV. Residual charge was removed before each voltage application.



Figure 10. Relation between impulse breakdown voltage and the radius of the embedded electrode. t = 11 (mm) and $r_p = 100 \text{ (mm)}$.



Figure 11. Relation between impulse breakdown voltage and the thickness of the plate. $r_e = 50 \text{ (mm)}$ and $r_p = 100 \text{ (mm)}$.



Figure 12. Relation between impulse breakdown voltage and the radius of the plate. $r_e = 25$ (mm) and t = 11 (mm).

Measurement was done more than 20 times for each condition of samples listed in Table 2 and the minimum value was employed as BDV.

In both cases of positive and negative impulse application, when $r_{\rm e}$ is larger than 15 mm there are good correlation between the measured value and the estimated value. When $r_{\rm e}$ is 15 mm, the measured value is smaller than the estimated value under positive impulse. The difference will be explained in DISCUSSION.

Figure 11 shows the relation between impulse breakdown voltage (BDV) and the thickness of the plate, t. In both cases of positive and negative impulse application, there are relatively good correlations between the estimated value and the measured value.

Figure 12 shows the relation between impulse BDV and the radius of the plate, r_p . In both cases, there are good correlations between the estimated value and the measured value except for the large r_p region under positive impulse. The difference in large r_p region is unexpected and further investigation is necessary.

5 DISCUSSION

5.1 PARTICULARITY IN SMALL r_e

Figure 13 shows the electric field distribution along the surface of the epoxy resin plate in the small r_e region. The radius of the center rod electrode was 5 mm. Electric field distribution was obtained using Ansoft Maxwell (Ansoft Japan Co., Ltd.) based on finite element method.



Figure 13. Variation of electric field distribution along the surface of the epoxy resin plate as a parameter of the radius of the embedded electrode. t = 11 (mm) and $r_p = 100 \text{ (mm)}$.

When r_e is smaller than 10 mm, the point of the maximum field strength appears on the surface of the center rod electrode. Then, the partial discharge is initiated at the surface of the center rod electrode and it will cover the surface around the center rod electrode easily because the electric field around the center rod electrode is high.

In the case where $r_e = 15$ (mm), the point of the maximum field strength appears close to just above the edge of the embedded electrode, however, the electric field at the surface of the center rod electrode is still high. When the partial discharge is initiated at the point of the maximum field strength, the electric field along the inner surface is enhanced by the existence of the partial discharge. Therefore, the inner surface is also supposed to be covered by the partial discharge easily.

Figure 14 shows the aspects of ac partial discharge when the radii of the embedded electrode are 15 and 25 mm, and the applied voltage is just above PDIV. As shown in Figure 14b, when the radius of the embedded electrode was 15 mm, the partial discharge appeared around the center rod electrode and around the position just above the edge of the embedded electrode, and sometimes covers the inner surface.

When the radius of the embedded electrode was 25 mm, the partial discharge appeared around the position just above the edge of the embedded electrode, as shown in Figure 14c. However, a faint partial discharge can be seen at the surface of the center rod electrode. Therefore, there still be the effect of field enhancement by the partial discharge when the radius of the embedded electrode was 25 mm.

According to this effect, flashover voltage of the inner surface will decrease and the BDV will become lower, in consequence.

5.2 PARTICULAR CASES OF BDV

As mentioned above, some particular cases appear when $r_{\rm e}$ is small.

(1) BDV- $r_{\rm e}$ characteristics

In Figure 10, the measured BDV is smaller than the estimated value in the case where $r_e = 15$ (mm) and the positive impulse application. The reason of the difference is explained by the effect of field enhancement mentioned in 5.1. The surface flashover voltage of inner surface is supposed to



(a) test sample [3]



(b) $r_{\rm e} = 15$ (mm) and the applied voltage was 32 kV_{rms}



(c) $r_{\rm e} = 25$ (mm) and the applied voltage was 36 kV_{rms}

Figure 14. Aspect of partial discharge under ac voltage. t = 11 (mm) and $r_p = 100 \text{ (mm)}$.

become the same as PDIV. Therefore, measured BDV became smaller than the estimated BDV.

In Figure 7, the measured BDV is smaller than the estimated value when r_e is smaller than 25 mm under ac voltage application. In the case of ac, the field enhancement is also one of the reason of the difference. Moreover, the effect of the residual charge on the surface discharge propagation is supposed. From the comparison between the measured BDV and the estimated value, the effect must be remarkable on the inner surface of short gap length up to 25 mm.

(2) BDV- $r_{\rm p}$ characteristics

In Figure 9, the measured BDV is smaller than the estimated BDV in the case of ac. In this case, the radius of the embedded electrode was 25 mm, then the effect mentioned

above was supposed to appear remarkably. BDV will become higher if the radius of the embedded electrode is chosen larger than 25 mm.

6 CONCLUSION

Solid insulated switchgear (SIS) has been developed as substitution for medium voltage SF_6 gas insulated switchgear. In the solid insulated switchgear, solid/gas insulation system is formed. For further miniaturization and higher stress design, the authors investigated on the surface insulation using the test sample, which was composed of the disc-shaped epoxy resin plate with embedded electrode. In the present study, the surface discharge propagation characteristics were measured with a disc-type epoxy plate and an equation which express the characteristics was obtained. The surface breakdown voltage was estimated based on the obtained equation. The results are summarized as follows.

- (1) The characteristics of the flashover voltage along the surface of the disk-type epoxy resin plate is found to be different from the conventional equation.
- (2) From the measurement of the surface flashover voltage, an equation which express the characteristics of the flashover voltage was obtained.
- (3) The estimation method of the breakdown voltage on the solid/gas insulation with embedded electrode based on the surface flashover voltage, distributed electrostatic capacity of the surface, and the propagation direction and the polarity of the surface discharge was proposed.
- (4) The estimated surface breakdown voltage based on the proposed estimation method agrees well with the measured value except for the region where the radius of the embedded electrode is small.
- (5) The difference between the estimated value and the measured value in the region where the radius of the embedded electrode is small was supposed to be caused by the effect of field enhancement by the partial discharge and the residual charge.

From the above, the surface breakdown voltage estimation procedure of the solid/gas composite insulation with embedded electrode is established.

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