Switching Surge Reduction of A Bi-Directional Dual Active Bridge DC-DC Converter with A Digital Operation

Mika Takasaki*, Yoichi Ishizuka*, Tamotsu Ninomiya*, Yutaka Furukawa** and Toshiro Hirose*** Nagasaki University*, Koga System Works** and Nishimu Electronics Industries Co.,Ltd.*** 1-14 Bunkyo-machi, Nagasaki-shi* Nagasaki, Japan* Tel.: +81 / (95) – 819-2556 Fax: +81 / (95) – 819-2556 E-Mail: isy2@nagasaki-u.ac.jp

Acknowledgements

The authors would like to thank Mr. Shohei Iwasaki, technical staff of Nagasaki University, for the various technical assistance.

Keywords

«Converter circuit», «DC power supply», «DSP», «IGBT»

Abstract

Recently, the bi-directional dc-dc converter has been focused on because of the huge demand for diversification of power supply network including battery. The dual active bridge (DAB) dc-dc converter is one of the most popular circuits for bi-directional applications because of its simple structure. However, power efficiency at light load is the intrinsic problem of a bi-directional DAB DC-DC converter. In this paper, the simple solution with digital operation for the problem is proposed and experiments are performed with 1kW system. This method can reduce a switching surge without other circuits such as snubber and improve power efficiency at light load. Therefore it can reduce loss of switching surge, and improve power efficiency. From the results, 37% maximum power efficiency improvement at light load is confirmed. Furthermore, this method is capable for control in the conventional method in the heavy load range. Consequently, it is possible to reduce the switching surge and realize high power efficiency in a wide load range.

Introduction

Recently, the bi-directional dc-dc converter has been focused on because of the huge demand for diversification of power supply network including battery. The DAB dc-dc converter is one of the most popular circuits for bi-directional applications because of its simple structure [1-5]. However, a switching surge and power efficiency at light load condition is the intrinsic problem [4].

Some research have been done to solve the problem, for instance, use of resonant type converter with snubber circuit [1], silicon carbide (SiC) power device and new magnetic materials [2], Quasi-ZCS operation with LC filter [3], and converter linked through superposition in additive polarity in series[4].

This paper proposes a simple solution for power efficiency improvement with digital operation. This method can improve power efficiency due to reduce a switching loss without adding other circuits such as snubber circuit.

BASIC OPERATION OF A DAB DC-DC CONVERTER

Figure 1 shows the circuit schematic of the conventional DAB dc-dc converter. Figure 2 shows conventional operating waveform [5]. In the conventional operation, the output power is operated by the phase-shift shown as φ between the primary voltage v_P and secondary voltage v_S of transformer.



Fig. 1: The circuit schematic of DAB dc-dc converter



Figure 3 shows the phasor diagram. V_P , V_S , V_L , and I are phasor symbols for v_P , v_S , v_L , i, respectively. When V_S is leading in phase than V_P , converter is operated in power running mode (Fig. 3 (a) and (b)), and when V_S is lagging than V_P , it is operated in power regenerative mode (Fig. 3 (c)). The output power Po can be obtained as

$$P_o = \frac{V_{in}V_{out}}{\omega L}\varphi(1-\frac{\varphi}{\pi}).$$
⁽¹⁾

The output power can be controlled with the phase difference φ . The waveform of the current *i* is changed by the load condition. In this paper, current *i* crossed the zero line in the State 2 is defined as a light load, and current *i* crossed the zero line in the State 1 is defined as a heavy load as shown in Fig. 2.



(a) power running mode (light load) (b) power running mode(heavy load) (c)power regenerative mode Fig. 3: Phasor diagram

INTRINSIC SURGE PROBLEM OF A DAB DC-DC CONVERTER

Well known problem of a DAB DC-DC converter is switching surge of when the load is in light condition. It is caused by the reverse recovery effect of the diode.

Figure 4 shows the switching surge generation mechanism when $V_{in} > V_{out}$. The surge occurs in the transition from State 1 (3) to State 2 (4), repeatedly. C_d is the parasitic capacitance of diode which is connected in parallel with the ideal diode, and L_{wire} is parasitic reactance. When the load is at the light load condition, the diodes D_4 is conducting in State 1. Then the switches Q_3 is turned on when state changes from State 1 to State 2. At this instantaneous moment, the diode D_4 is switched from a forward bias condition to a reverse bias condition immediately, and it leads to resonance of C_d and L_{wire} . Because of these reasons, the switching surge occurs. Similarly, when $V_{in} < V_{out}$, the surge occurs in the transition from State 2 (4) to State 3 (1). it occurs in the bridge on the primary side.

Commonly, to protect the switches from the switching surge, snubber circuit are applied [2]. However, the power loss at the snubber circuit can't be ignored at the light load condition. The other way, the resonant converter type is also popular, but the additional components are needed.



PROPOSED OPERATING METHOD

We propose the software-based compensation method for basic DAB bi-directional dc-dc converter which can be reduce the switching surge reduction at the light load, without any of additional circuits such as the snubber circuits or resonant circuits. Figure 5 shows idealized waveform of the proposed operating method. With this method, it can be easily change buck mode and boost mode operation. When $V_{in} < V_{out}$, as it can be seen from the waveforms, the direction of primary side current of transformer i during each on-time of Q₁ and Q₂, is restricted to avoid the crossing the zero line. Due to the restriction of the change of the direction of the current, the zero-current-switching-on can be realized for Q₁ and Q₂. To analyze the characteristics of the circuit, Extended State-Space Averaging Method [5] is applied. The analysis has been done for each of buck mode and boost mode operation, respectively. This converter has six operational states in one switching period for each of the buck and boost mode operation, respectively. The elements are treated as ideal in equivalent circuit.



Fig. 5: Idealized wave form for proposed operating at the light load: (a) buck mode; (b) boost mode.

Buck Mode Operation

In buck mode, the primary side switches Q₁ and Q₂ are turned-on twice in the period. Firstly, Q₁ and Q₂ are turn-on at t = 0 and $T_s / 2$. Secondly, they are turn-off at t = A and $T_s / 2 + A$. Thirdly, they are turn-on at $t = \varphi$ and $T_s / 2 + \varphi$. Fourthly, they are turn-off at $t = T_s / 2$ and T_s . Equivalent circuits corresponding to each state in buck mode operation are shown in Fig. 6, where \hat{v}_o is the low-frequency component of V_o . For analysis, solving for i_L and i_{c_o} for $0 \le t \le A$ (State 1)

$$i_{L} = \frac{V_{i} + \hat{v}_{0}}{L} t + i(0), \qquad i_{C} = -i_{L} - \frac{\hat{v}_{o}}{R_{L}}$$
(2)

for $A \le t \le \varphi$ (State 2)

$$i_L = 0, \qquad i_C = -i_L - \frac{\hat{v}_o}{R_L}$$
 (3)

for $\varphi \leq t \leq \pi$ (State 3)

$$i_{L} = \frac{V_{i} - \hat{v}_{0}}{L} \{ t - (D_{a} + D_{b})T_{s} \}, \qquad i_{C} = i_{L} - \frac{\hat{v}_{o}}{R_{L}}$$
(4)

for $\pi \le t \le \pi + A$ (State 4)

$$i_{L} = -\frac{V_{i} + \hat{v}_{0}}{L} \left(t - \frac{1}{2}T_{s}\right) + \frac{V_{i} - \hat{v}_{0}}{L} D_{c}T_{s}, \qquad i_{C} = i_{L} - \frac{\hat{v}_{o}}{R_{L}}$$
(5)

for $\pi + A \le t \le \pi + \varphi$ (State 5)

$$i_L = 0, \qquad i_C = i_L - \frac{\hat{v}_o}{R_L}$$
(6)

for $\pi + \varphi \le t \le 2\pi$ (State 6)

$$i_{L} = -\frac{V_{i} - \hat{v}_{0}}{L} \left\{ t - \left(\frac{1}{2} + D_{a} + D_{b}\right)T_{s} \right\}, \qquad i_{C} = -i_{L} - \frac{\hat{v}_{o}}{R_{L}}.$$
(7)

From Fig. 5, it is clear that $D_a + D_b + D_c = 1/2$, $i_L(0) = i_L(2\pi)$ and $i_L(A) = 0$. Using the preceding relationships,

$$i_{L}(0) = i_{L}(2\pi) = -\frac{V_{i} - \hat{v}_{0}}{L} D_{c} T_{s}$$
(8)

and



(c) State 3

(f) State 6

Fig. 6 Equivalent circuit of buck mode operation: (a) State 1; (b) State 2; (c) State 3; (d) State 4; (e) State 5; (f) State 6

The average value of i_c in each state is calculated with

$$i_{c_{avel}} = \frac{1}{2} \{ (\frac{V_i - \hat{v}_o}{L} D_c T_s - \frac{\hat{v}_o}{R_L}) - \frac{\hat{v}_o}{R_L} \} = \frac{1}{2} \frac{V_i - \hat{v}_o}{L} D_c T_s - \frac{\hat{v}_o}{R_L}$$
(10)

$$i_{c_ave2} = -\frac{\hat{v}_o}{R_L} \tag{11}$$

$$i_{c_ave3} = \frac{1}{2} \{ -\frac{\hat{v}_o}{R_L} + (\frac{V_i - \hat{v}_o}{L} D_c T_s - \frac{\hat{v}_o}{R_L}) \} = \frac{1}{2} \frac{V_i - \hat{v}_o}{L} D_c T_s - \frac{\hat{v}_o}{R_L}$$
(12)

$$i_{c_ave4} = \frac{1}{2} \{ (\frac{V_i - \hat{v}_o}{L} D_c T_s - \frac{\hat{v}_o}{R_L}) - \frac{\hat{v}_o}{R_L} \} = \frac{1}{2} \frac{V_i - \hat{v}_o}{L} D_c T_s - \frac{\hat{v}_o}{R_L}$$
(13)

$$i_{c_ave5} = -\frac{\hat{v}_o}{R_L} \tag{14}$$

$$i_{c_ave6} = \frac{1}{2} \{ -\frac{\hat{v}_o}{R_L} + (\frac{V_i - \hat{v}_o}{L} D_c T_s - \frac{\hat{v}_o}{R_L}) \} = \frac{1}{2} \frac{V_i - \hat{v}_o}{L} D_c T_s - \frac{\hat{v}_o}{R_L}.$$
(15)

Hence,

$$\overline{i_c} = i_{c_ave1} \times D_a + i_{c_ave2} \times D_b + i_{c_ave3} \times D_c + i_{c_ave4} \times D_a + i_{c_ave5} \times D_b + i_{c_ave6} \times D_c$$

$$=\frac{2D_{a}^{2}T_{s}V_{i}}{L}\cdot\frac{V_{i}+\hat{v}_{o}}{V_{i}-\hat{v}_{o}}-\frac{\hat{v}_{o}}{R_{L}}.$$
(16)

The results of static characteristics are obtained by letting $d\hat{v}_o / dt = 0$, therefore

$$\frac{d\hat{v}_o}{dt} = \frac{1}{C} \frac{1}{c}$$

$$P_o = \frac{2D_a^2 T_s}{L} \cdot \frac{V_o + V_i}{V_o - V_i} \cdot V_i V_o.$$
(17)

Using $D_a T_s = A$,

$$P_o = \frac{2A^2}{T_s L} \cdot \frac{V_o + V_i}{V_o - V_i} \cdot V_i V_o \tag{18}$$

where

$$A = \frac{V_i - V_o}{V_i + V_o} (\frac{1}{2}T_s - \varphi).$$
(19)

Boost Mode Operation

In boost mode, the secondary side switches Q_3 and Q_4 are turned-on twice in the period. Firstly, Q_3 and Q_4 are turn-on at $t = \varphi$ and $T_s / 2 + \varphi$, respectively. Secondly, they are turn-off at t = B and $T_s / 2 + B$. Thirdly, they are turn-on at $t = T_s / 2$ and 0. Fourthly, they are turn-off at $t = T_s / 2 + \varphi$ and B. Equivalent circuits corresponding to each state in boost mode operation are shown in Fig. 7.



Fig. 7 Equivalent circuit of boost mode operation: (a) State 1; (b) State 2; (c) State 3; (d) State 4; (e) State 5; (f) State 6

For analysis, equation is formularized for each state. For $0 \le t \le \varphi$ (State 1)

$$i_{L} = \frac{V_{i} + \hat{v}_{0}}{L}t, \qquad i_{C} = -i_{L} - \frac{\hat{v}_{o}}{R_{L}}, \qquad (20)$$

for $\varphi \le t \le B$ (State 2)

$$i_{L} = \frac{V_{i} - \hat{v}_{0}}{L} (t - D_{a}T_{s}) + \frac{V_{i} + \hat{v}_{o}}{L} D_{a}T_{s}, \qquad i_{C} = i_{L} - \frac{\hat{v}_{o}}{R_{L}},$$
(21)

for $B \le t \le \pi$ (State 3)

$$i_L = 0, \qquad i_C = -\frac{v_o}{R_L},$$
 (22)

for $\pi \le t \le \pi + \varphi$ (State 4)

$$i_{L} = -\frac{V_{i} + \hat{v}_{0}}{L} \left(t - \frac{1}{2}T_{s}\right), \qquad i_{C} = i_{L} - \frac{\hat{v}_{o}}{R_{L}},$$
(23)

for $\pi + \varphi \le t \le \pi + B$ (State 5)

$$i_{L} = -\frac{V_{i} - \hat{v}_{0}}{L} \{t - (\frac{1}{2} + D_{a})T_{s}\} - \frac{V_{i} + \hat{v}_{o}}{L} D_{a}T_{s}, \qquad i_{C} = -i_{L} - \frac{\hat{v}_{o}}{R_{L}},$$
(24)

for $\pi + B \le t \le 2\pi$ (State 6)

$$i_L = 0, \qquad i_C = -\frac{\hat{v}_o}{R_L}.$$
 (25)

From Fig. 5, it is clear that $D_a + D_b + D_c = 1/2$, and $i_L(B) = 0$. Using the preceding relationships

$$D_b = -\frac{V_i + \hat{v}_o}{V_i - \hat{v}_o} D_a \tag{26}$$

The average value of i_c in each state is calculated with

$$i_{c_avel} = \frac{1}{2} \{ -\frac{\hat{v}_o}{R_L} + (-\frac{V_i + \hat{v}_o}{L} D_a T_s - \frac{\hat{v}_o}{R_L}) \} = -\frac{1}{2} \frac{V_i + \hat{v}_o}{L} D_a T_s - \frac{\hat{v}_o}{R_L}$$
(27)

$$i_{c_ave2} = \frac{1}{2} \{ (\frac{V_i + \hat{v}_o}{L} D_a T_s - \frac{\hat{v}_o}{R_L}) - \frac{\hat{v}_o}{R_L} \} = \frac{1}{2} \frac{V_i + \hat{v}_o}{L} D_a T_s - \frac{\hat{v}_o}{R_L}$$
(28)

$$i_{c_ave3} = -\frac{\hat{v}_o}{R_L}$$
(29)

$$i_{c_ave4} = \frac{1}{2} \{ -\frac{\hat{v}_o}{R_L} + (-\frac{V_i + \hat{v}_o}{L} D_a T_s - \frac{\hat{v}_o}{R_L}) \} = -\frac{1}{2} \frac{V_i + \hat{v}_o}{L} D_a T_s - \frac{\hat{v}_o}{R_L}$$
(30)

$$i_{c_ave5} = \frac{1}{2} \{ (\frac{V_i + \hat{v}_o}{L} D_a T_s - \frac{\hat{v}_o}{R_L}) - \frac{\hat{v}_o}{R_L} \} = \frac{1}{2} \frac{V_i + \hat{v}_o}{L} D_a T_s - \frac{\hat{v}_o}{R_L}$$
(31)

$$i_{c_ave6} = -\frac{\hat{v}_o}{R_L}.$$
(32)

Hence,

$$\overline{i_c} = -\frac{2D_a^2 T_s V_i}{L} \cdot \frac{V_i + \hat{v}_o}{V_i - \hat{v}_o} - \frac{\hat{v}_o}{R_L}.$$
(33)

The results of static characteristics are obtained by letting $d\hat{v}_o / dt = 0$, therefore

$$P_o = \frac{2D_a^2 T_s}{L} \cdot \frac{V_o + V_i}{V_o - V_i} \cdot V_i V_o . \tag{34}$$

Using $D_a T_s = \varphi$

$$P_o = \frac{2\varphi^2}{T_s L} \cdot \frac{V_o + V_i}{V_o - V_i} \cdot V_i V_o.$$
(35)

B is calculated as

$$B = (D_a + D_b)T_s = \frac{2V_o}{V_o - V_i}\varphi.$$
(36)

Output Power

From the above, the analysis for both of buck and boost mode operation can be done in uniformly. For the analysis result, the output power Po can be obtained as

$$P_o = \frac{2X^2}{T_s L} \cdot \left| \frac{V_i + V_o}{V_i - V_o} \right| \cdot V_i V_o.$$
(37)

In buck mode, X=A, and in boost mode, $X=\varphi$.

Operation Shift between Light and Heavy Load

In the light load, with the output power increasing, the periods of which all switches turned OFF $(A \sim \varphi, \pi + A \sim \pi + \varphi, B \sim \pi, \pi + B \sim 2\pi)$ becomes shorter. The periods, equal to zero seconds, it is the boundary between light load and heavy load. Therefore, in the heavy load condition, the only conventional phase-shift operation is active. From the results, it can be seen that it is possible to control the output power seamlessly despite of the load condition.

EXPERIMENTAL RESULTS

To verify the proposed operation validity, we perform some experiments with the prototype circuit. The main circuit is DAB dc-dc converter without additional circuits like snubber circuit. We had closed loop operation experiments with DSP TI TMS320F28335. Experimental parameters are shown in Table I. Figure 8 and Fig. 9 show drive signal generating mechanism. Dead time of each switch is 1µs.

Item	Symbol	Specification
Transformer		
1) Turns ratio	a	1:1
2) Leakage inductance(primary-referred)	L	110µH
Converter		
1) Rated output power	Po	1kW
2) Rated input direct voltage	V _{in}	150V
3) Rated output direct voltage	V _{out}	150V
4) Switching frequency	$f_{\rm s}$	20kHz
5) Absolute maximum ratings of IGBT collector-emitter	$v_{\rm CE}$	600V
6) On resistance of IGBT	r _t	50mΩ
7) Absolute maximum ratings of diode	$i_{ m F}$	30A
8) Forward voltage of diode	$v_{\rm F}$	0.8V
9) Recovery time of diode	t _{rr}	0.1µs

Table I: Specification of Bidirectional DAB dc-dc converter



Mask signal Fig. 8 Masked drive signal generating mechanism.



Fig. 9 Mask signal generating mechanism by PWM peripheral in DSP.

Figure 10 shows the waveform of the corrector-emitter voltage and the corrector current of the low voltage side bridge of the buck converter. Figure 10(a) shows the result of the conventional operation and Figure 10(b) shows the result of the proposed operation. Comparing with these results, it can be seen that 99% of voltage surges and 100% of current serge of reduction.



(a) the prototype operation (b) the proposed operation Fig. 10 The waveforms in buck mode: (a) the prototype operation $(V_{in}=200V, V_{out}=150V, P_o=569W)$; (b) the proposed operation. $(V_{in}=200V, V_{out}=150V, P_o=566W)$

Figure 11 shows the waveform of the boost converter. Comparing with these results, it can be seen that 99% of voltage surges of reduction and 100% of current serge of reduction.



Fig. 11 The waveforms in boost mode: (a) the prototype operation (V_{in} =100V, V_{out} =150V, P_o =687W); (b) the proposed operation. (V_{in} =100V, V_{out} =150V, P_o =686W)

Figure 12 shows the power efficiency results for the both of the conventional and the proposed operation. It can be seen that the power efficiency of buck mode can be apparently improved by up to 37% using the proposed operation at 100W as shown in Fig. 12 (a). It can be seen that the power efficiency of boost mode can be apparently improved by up to 30% at 100W as shown in Fig. 12 (b).



Conclusion

By the analysis of the circuit operation and the some experiments, the validation of the proposed operation for DAB dc-to-dc converter is revealed. The operation method with digital operation can reduce switching surges without other circuits like snubber circuit. From the experiment results, the 99% of the maximum voltage surge reduction and 100% of the maximum current serge reduction at the light load is confirmed. Furthermore, due to the surge reduction method, 37% maximum power efficiency improvement can be confirmed at light load. Also the operation can be applied to any condition from light to heave load seamlessly.

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